

Method of controlling an electrochemical machining process.

FIELD OF THE INVENTION

The invention relates to a method of controlling a process of electrochemically machining an electrically conductive workpiece as recited in the preamble of claim 1 as well as to a method of electrochemically machining as recited in the preamble of claim 30. The invention further relates to an arrangement for a performing a method of controlling a process of electrochemically machining as recited in the preamble of claim 39 as well as to an arrangement of electrochemically machining as recited in the preamble of claim 68.

BACKGROUND OF THE INVENTION

Electrochemically machining is a process in which an electrically conductive workpiece is dissolved at the location of an electrode while electrolyte and electric current is supplied. For this purpose, the electrode is brought in proximity of the workpiece and, while electrolyte is fed into the gap between the workpiece and the electrode, a current is passed through the workpiece and the electrode via the electrolyte, the workpiece being positive with respect to the electrode. The current may be supplied in the form of a constant current while maintaining a sufficient gap to replenish the electrolyte simultaneously. This method allows a high rate of removal of dissolved material. The current may also be supplied in the form of pulses having specific amplitude and duration, the electrolyte being replenished in the interval between the machining pulses. During replenishing the gap between the workpiece and the electrode is then made larger than during machining. The small gap during machining allows a higher machining accuracy. During application of the current, the electrode and the workpiece are moved towards each other with a given feed rate, as a result of which the electrode forms a cavity or eventually a hole in the shape of the workpiece, the shape of this cavity or hole corresponding to the shape of the electrode. This process can be used, for example, for making intricate cavities or holes in hard metals or alloys therefrom.

However, in practice unwanted process conditions may arise that may degrade the normal machining operation. This may be due for instance due to the generation of spark discharges that may occur within the gap. Such spark discharges may give rise to damages to

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the electrode and the workpiece. Another undesired process condition is the presence of gas-filled bubbles or cavities within the machining gap, causing non-conducting regions in the electrolyte. This may lead to an undesired an undefined surface roughness of the workpiece. These gas-filled bubbles may rise owing to a temperature increase or pressure drop along the flow channel. If the growth is caused by temperature increase, due to for example the passage of current, boiling occurs. If the growth is due to pressure reduction, cavitation is said to have occurred. Another undesired process condition is called choking, which is induced by a maximum in mass flow-rate as determined by the smallest area of the gap. A further undesired process condition is the occurrence of a passivating or a non-conductive layer on the workpiece surface.

To avoid such undesired process conditions it is known, from for instance from the International Patent Publication numbered WO 99/34949, document D1 in the list of referred documents that can be found at the end of this description, to measure with antenna means high frequent electromagnetic waves originated from the gap. These are believed to be indicative of so-called partial discharges which are believed to be precursors of a spark discharge. However, measurement of electromagnetic waves is prone to disturbances present in an industrial environment. Also no information with respect to the occurrence of other undesired process conditions as mentioned above is being derived from this information.

From the International Patent Publication numbered WO 97/03781, document D2 in the list of referred documents that can be found at the end of this description, it is known to analyze the waveform induced by the applied current to find the optimum limits for applying pulses of opposite polarity to remove passivation layers. To this end, during a test preceding the machining of the workpiece, the amplitude of the pulses is varied and the optimum limits are derived from the resulting measured parameters, such as the occurrence of a global minimum in the voltage across the gap. However, this test does enable monitoring the occurrence of passivation, let alone during machining itself. Further, if the process conditions change significantly, such as the parameters of the applied current or the electrolyte flow, the test must be repeated.

OBJECT AND SUMMARY OF THE INVENTION

In consequence, amongst other things, it is an object of the invention to obviate above-mentioned disadvantages. In particular an object of the invention is obtaining a method of controlling a process of electrochemically machining, which allows to monitor one or more process conditions and to adjust the one or more process parameters in order to avoid

undesired process conditions, especially while maintaining a constant gap width. According to one of its aspects a method according to the invention is characterized as recited in the characterizing part of claim 1.

Varying process conditions give rise to a change of a measured voltage present for instance across a gap between the electrode and the workpiece. By choosing the measuring period such that a change can be detected within this measuring period, the change as a function of time or shortly the form function defining the type of change within the measuring period can be distinguished. This form function can be decomposed in to its constituent frequency components or frequency spectrum. By employing the information present in this frequency spectrum, indicators indicative of several process conditions, such as for example those mentioned above, can be obtained during the process of machining. It is found that the occurrence of a first process condition influences only a specific part of the spectrum, while a second process condition influences either these part in another way or influences another part. As the information may be obtained continuously, the process may be continuously controlled in response thereto.

More specifically, it has found to be advantageous to employ the amplitudes of the frequency components of the frequency spectrum, according the method of claim 2.

A next advantageous method is to use a harmonic frequency of the waveform according to the method of claim 3. Harmonic frequencies are hereby being defined as an integer multiple of the elementary frequency as determined by the length of the measuring period. Especially the lowest harmonic frequencies appear to be useful in defining process conditions.

Decomposing the form function according to a Fourier series, by a well known Fourier transformation, according to the method of claim 4, has been found useful as a practical mathematical embodiment. Although a form function may be decomposed in several elementary functions, each with a specific frequency, trigonometric functions such as sine and cosine appear to be most useful.

Further it is noted that a conversion of the measured voltage from the time domain to the frequency domain, such as is done by the above-mentioned Fourier transformation, is not the only method to obtain the spectral composition. The spectral information may equally be obtained by performing an autocorrelation in the time domain or by employing suitable frequency band filtering.

A further advantageous method employs only the signs of the Fourier coefficients, according to the method of claim 5. Absolute values may vary in a high degree,

while signs, and especially the relative signs, are found to be a more stable indicator of process conditions.

It has been found that a first process condition of relatively low current density, may be assigned to the absence of Fourier coefficients, according to the method of

claim 6. A next process condition indicating the presence of gas-filled cavities in the electrolyte, is assigned to Fourier coefficients with alternating signs, according to the method of claim 7.

A further process condition indicating a high current density, may be assigned to the presence of number of Fourier coefficients with equal signs, according to the method of claim 8.

Another advantageous method is obtained by taking into account frequencies above a certain value, and monitoring only a change therein, according to the method of claim 9. This is found to be indicative of approaching a process condition susceptible of electric discharges in the gap. It has been found particular useful to monitor the running average of the corresponding amplitudes, according to the method of claim 10.

It has been found that several process control parameters may be adjusted, in response to the occurrence of changing process situations, to avoid undesired process conditions. In particular changing the duration of a current that is being applied, according to the method of claim 11, has found to be useful. Applying the current intermittently, has the effect of reducing heating the electrolyte and therefore changing a process situation of boiling or cavitating.

A particular advantageous method is obtained when, during applying current intermittently, the electrode and the workpiece are moved relatively to each other in an oscillatory harmonic manner or in repeated non-harmonic manner, according to the method of claim 12. This allows increasing the electrolyte pressure in the gap when current is applied. This consequently counters the generation of bubbles in the electrolyte.

Applying a sequence of current pulses when a small distance between electrode and workpiece is present, according to the method of claim 13, has the advantage of further countering the generation of bubbles.

An undesired process condition is characterized by the generation of a passivation layer on the workpiece, such as an oxide layer which forms a barrier between the workpiece and the electrolyte. An advantageous method is then obtained by applying current pulses of an opposite polarity according to method of claim 14. This causes, as is known from document D2 in the list of referred references, the dissolving of the passivation layer.

A further undesired process situation may be characterized by a lack of machining accuracy. A useful process control parameter to improve a machining accuracy is the addition of passivation pulses according to the method of claim 15.

A next undesired process condition may arise due to a deposition of
5 contaminating materials on the electrode. This leads to inaccurate machining as the distance between the electrode and workpiece may change in an undefined manner, either local or global. Especially in case of electrolyte which has been used for a long time, a deposition of dissolved metal ions of the dissolved workpiece may occur as black layer along the total area of the electrode tool. This is called plating and may effect the geometrical dimensions.

10 Another contamination is deposition of a hydroxide layer near the electrolyte outflow opening within the gap. This does not only effect the geometrical dimension but also the flow rate of the electrolyte. An advantageous process parameter is then the application of electrode cleaning pulses according to the method of claim 16.

A special next embodiment is obtained in a method where the workpiece and
15 the electrode are brought in contact with each other prior to machining in order to calibrate the mutual position. By applying the electrode cleaning pulses just before this action, according to the method of claim 17, an accurate calibration is obtained.

In a method wherein the electrode and the workpiece are moved relatively to
20 each other in a repeated movement and the current pulses are applied when the distance between both is small, the machining accuracy may be high, due to the short distance allowable, but the productivity low, due to a slow flow of electrolyte. A useful process control parameter to adjust is the duration of the pulse periods, according to the method of claim 18. It has been found that decreasing the pulse period, may increase the amount of current which can be applied.

25 An advantageous value of the reduced pulse period is obtained according to the method of claim 19. The time needed for generation of nuclei preceding the formation of gas bubbles, such as for example hydrogen gas, is a practical criterion for determining the reduced pulse period. This is useful when higher current densities are being employed, normally leading to formation of gas-filled bubbles. With such extreme short pulses no time
30 is left for formation of bubbles.

Although specific values may depend on specific circumstances, a first embodiment of the method employs values according to the method of claim 20.

An important characteristic of such extreme short pulses is the steep pulse forefront, which should have values according to the method of claim 21.

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In a process where sequences of intermittently applied electric current pulses are being applied, pauses between the pulses should preferably be chosen according to the method of claim 22, with specifically values according to the method of claim 23.

In a process wherein the electrode and the workpiece are moved relatively to each other in an oscillatory movement and the current is being supplied intermittently when the distance between both is small, a further advantageous process control parameter is the relative phase shift between the movement and the start of applying the current, according to the method of claim 25.

In the same process this also proves to be the case for the electrolyte pressure, according to the method of claim 26, and for the relative machining speed according to the method of claim 27.

In a process wherein the current is applied in pulses, it is found advantageous to take the pulse period substantially equal to the measuring period, according to the method of claim 28. In such a process, the process conditions are not stable within a pulse period, leading to a significant and informative change of the measure voltage during this pulse period.

In a process wherein the current is applied substantially continuously, an advantageous method is obtained by selectively choosing the measuring period, according to the method of claim 29. Although generally such a process should have stable process conditions, and therefore no significant change in the measured voltage, deviations therefrom, may be detected. Such as those occurring at start-up, or at a disturbance during the process and or at reaching an end of the machining.

Further, control of some of the previously mentioned process control parameters appear to be particular useful taken alone or in combination, in order to avoid undesired process conditions.

A first advantageous method of electrochemical machining according to the invention is obtained by combining a method wherein the electric current is being supplied continuously with a method wherein the current is supplied intermittently, according to the method of claim 30. According to the first method, to be regarded as course material removing step, a large gap distance may be maintained and a high flow of electrolyte, causing a high rate of removal of material. According to the second method, to be regarded as a workpiece final shaping process, a subsequent accurate shaping may be obtained, due to a smaller gap. Such an accurate shaping not being feasible with the first without leading to undesired process conditions.

A further advantageous embodiment is obtained by applying in the workpiece final shaping step, a sequence of intermittently applied current according to the method of claim 31. This extends the ability to improve either the machining accuracy by allowing a smaller gap or either the ability to improve the surface quality of the workpiece, both without reaching undesired process conditions.

A next advantageous embodiment is obtained by applying in the workpiece final shaping step, passivation pulses according to the method of claim 36. This improves the machining accuracy in a high degree, as in front of the electrode a passivation layer will be dissolved and substantially less will be dissolved at the side of the electrode. Dissolving of the workpiece will therefore happen mainly in front of the electrode. Again undesired process conditions may be postponed in this manner.

A subsequent advantageous embodiment is obtained by applying pulses of an opposite polarity, according to the method of claim 37. Thus enabling the removal of passivation layers on the workpiece.

Also a method wherein electrode cleaning pulses are being applied according to the method of claim 38, appear to result in a method with a longer range of desired process conditions.

Further advantageous aspects of the invention are relating to an arrangement for electrochemically machining, are recited in the independent claims 39 and 68 respectively and in the dependent claims 40- 67 and 69 - 76 respectively.

BRIEF DESCRIPTION OF THE DRAWINGS

These and further aspects and advantages of the invention will be apparent from and elucidated in more detail hereinafter with reference to the disclosure of preferred embodiments, and in particular with reference to the appended figures in which,

Fig. 1 illustrates schematically an arrangement for electrochemically machining for carrying out the method of the invention;

Fig. 2 shows schematically a control circuit for controlling the arrangement of Fig. 1 in accordance with the method of the invention;

Fig. 3 shows an embodiment of power supply circuitry to be used in the control circuit of Fig.2;

Fig. 4 illustrates a method of electrochemical machining;

Fig. 5 illustrates another method of electrochemically machining;

Fig. 6 illustrates a further method of electrochemically machining;

Fig. 7 shows characteristic examples of measured voltages during a predetermined measuring period induced by applying current to an electrochemical cell;

Fig. 8 shows a first embodiment of the method according to the invention for determining a characteristic waveform of a measured voltage such as shown in Fig. 7 and
5 deriving spectral information therefrom;

Fig. 9 illustrates the method of Fig. 8;

Fig. 10 shows an example of spectral information obtained with the method described with reference to Fig. 8 and Fig. 9;

Fig. 11 shows a first example of assigning specific process conditions to
10 spectral information, in accordance with an embodiment of the invention;

Fig. 12 shows a further embodiment of the method according to the invention for deriving spectral information;

Fig. 13 shows an embodiment of a control unit for carrying out the method of the invention,

Fig. 14 to Fig.18 are showing several methods according to the invention of
15 controlling a process of electrochemically machining,

Fig. 19 shows an example of Fourier coefficients C_k corresponding to type I process conditions as a function of gap size S and minimum applied voltage U_{min} ;

Fig. 20 shows an example of Fourier coefficients C_k corresponding to type II
20 process conditions as a function of electrolyte pressure P_{in} ,

Fig. 21 shows an example of Fourier coefficients C_k corresponding to type III process conditions as a function of gap size S and

Fig. 22 shows another example according to the invention of controlling a process of electrochemically machining.

DESCRIPTION OF THE EMBODIMENTS

Fig. 1 illustrates schematically an arrangement for electrochemically machining a workpiece 1. The workpiece 1 is carried by a table 2 which moves with a feed rate V_1 , by means of first positioning means 4, towards an electrode tool 3. The workpiece 1,
30 the electrode tool 3 and the table 2 are electrically conductive. The electrode tool 3 may be moved relative to the workpiece 1 with an electrode feed rate V_2 by means of second positioning means 5. The second positioning means 5 may cause the electrode tool 3 to perform an oscillatory movement such as a harmonic movement or a non-harmonic repeated movement relative to the workpiece 1. This may be realized by means of, for example a

crank shaft which is driven by a motor or by hydraulic means. The first positioning means 4 may comprise linear displacement means comprising a threaded shaft. The first positioning means 4 are controlled by a first positioning control signal S1 while the second positioning means 5 are controlled by a second positioning control signal S2. The workpiece 1 may be made of, for example a hard metal such as titanium or an alloy, such as chromium containing steel. An electrolyte 18, for example an aqueous solution of nitrates of alkaline metals, flows in the gap 6 between the workpiece 1 and the electrode tool 3 and is circulated with an input pressure P_{in} and an output pressure P_{out} from a reservoir, not shown in the figure, by suitable circulating means 7 employing a pump. The electrode tool 3 and the table 2 are connected to a control circuit 8 comprising an electric power source that induces an electric current between the electrode tool 3 and the table 2 via the electrolyte 18. The induced electric current may be constant or pulsed. The normal polarity being that the table 2, and consequently the workpiece 1, is positive relative to the electrode tool 3. During current pulses of normal polarity the metal of the workpiece 1 dissolves in the electrolyte. A position of the table 2 is measured by position sensing means 9, which supplies a corresponding position signal Z to the control circuit 8. The part of the arrangement shown in Fig. 1 excluding the control circuit 8 will be denoted hereinafter to as the electrochemical process unit 10.

Fig 2 shows schematically an embodiment of the control circuit 8 of Fig. 1 in more detail. The control circuit 8 is separated in a power supply unit 11, a control unit 12, monitoring means 13 and manual control means 14. The power supply unit 11 generates the required electric current I or voltage V, which is applied to the electrochemical process unit 10. The power supply unit 11 may comprises several power supply sub units, not shown in the figure, to generate either a constant current or several types of pulsed current. It is noted that the power supply sub units do not need to be integrated in one unit but may be arranged in a system of cooperating independent sub units. The control unit 12 controls the operation of the power supply unit 11 with power supply control signals SEL1, SEL 2, CI1, CI2.... in accordance with the employed method of controlling and with received measurement signals U_m , Z, P.... from the electrochemical process unit 10. The monitoring means 13 may comprise simple visual indicators, measurement devices or general display means. The manual control means 14 are used by an operator and may comprise simple switching means as well as general keyboard. It is further noted that the control unit 12 may be constituted either in part or as a whole as dedicated hardware with a specific function or as a general-purpose computer loaded with a specific program.

Fig. 3 shows in more detail an embodiment of the power supply unit 11 of Fig. 2 for carrying out the method according to the invention. The power supply unit 11 comprises a constant current source 15, which supplies a continuous current whose magnitude is controlled by the control signal CI1, via an interface 16, which may be formed by, for example, digital-to-analog converters. The control signal CI1 is generated by the control unit 12. The negative terminal of the current source 15 is connected to the electrode tool 3 via an optional current measuring circuit 17. This current measuring circuit 17, which may comprise a single electric resistor connected in serial, is used to derive a measurement voltage Um1, indicative of the current applied to the electrochemical process unit 10. The positive terminal of the constant current source 15 is connected to switching means 19, which is controlled by a selection signal SEL1, generated by the control unit 12. A voltage Um2 measured across the power supply output terminals 20 and 21 is measured by voltage measuring circuit 22. It is remarked that the current measuring unit 17 and/or the voltage measuring unit 22 may be embodied as a special measuring unit 23 located apart from the power supply unit 11 but close to the electrochemical process unit 10.

The power supply unit 11 further comprises a constant voltage source 23 for supplying a constant voltage to the electrochemical process unit 10. The amplitude of the voltage generated by the constant voltage source 23 is controlled by a control signal CU1 via an interface 24. An output terminal of the constant voltage source 23 is connected to switching means 25 which is controlled by a selection signal SEL2. The control signal CU1 and the selection signal SEL2 are generated by the control unit 12. As will be elaborated later in more detail, an additional voltage, which may be of the opposite polarity, may be applied advantageously to the electrochemical process unit 10.

Alternately, a pulsed current source 26 is present for supplying current in pulse like periods. The pulsed current source 26 is controlled by a control signal CI2 via an interface 27. It is noted that not only the amplitude of the supplied current may be controlled but also the relation of pulse amplitude versus time. The pulsed current source 26 may be connected to the electrochemical process unit 10 by switching means 28, which are controlled by a selection signal SEL3. It is noted that special circuitry is required for generating a pulsed current, due to requirements to pulse shape and pulse duration. Although examples will be given hereinafter, typical pulse periods may be expressed in 1 to 100 ms.

Finally a special pulsed current source 29 is present for generating current during extreme short periods, ranging from 10 to 100 μ s with an extreme steep forefront of approximately 0,5 μ s. The special pulsed current source 29 is controlled by a control signal

CI2 via an interface 30 and selected by a selection signal SEL4, which controls switching means 31.

Curve I in Fig. 4 represents the variation of the size $S(t)$ of the gap 6 between the workpiece 1 and the electrode tool 3 during applying a constant current. Curves II and III in Fig.4 show the variation of the measured voltage U_m across the gap 6 and the current I_s applied through the gap 6 respectively. In practice, during the electrochemical machining process, the gap 6 is kept substantially constant by choosing the feed rate V_1 of the table 2 equal to the rate by which the metal of the workpiece 1 dissolves. However, small variations of the size $S(t)$ may occur, such as indicated as an example with curve I. These variations may be due to varying process conditions, such as changing characteristics of the surface of the workpiece 1 or pollution of the electrode tool 3 or electrolyte 18. These variations in size $S(t)$ may lead to variations in the measured voltage U_m , during a measuring period T_m , as indicated with curve III. For instance, a smaller size $S(t)$ may lead to a smaller voltage U_m , due to a smaller resistance formed by the smaller amount of electrolyte 18 in the gap 6.

Curve I in Fig. 5 represents the variation of the size $S(t)$ of the gap 6 between the workpiece 1 and the electrode tool 3 during an oscillatory movement relative to each other with a maximum size S_{max} and a minimum size S_{min} and applying pulsed current I_s according to curve II. Curve III shows the measured voltage U_m across the gap 6. If no current I_s is applied, no voltage U_m is present. However, when a current I_s of amplitude I_{s1} is applied, the measured voltage U_m rises quickly. The distance $S(t)$, in an initial stage, is comparatively large and the electrolyte flow may be turbulent and containing vapor and gas bubbles. Therefore the resistance across the gap 6 is relatively high, which is apparent from the first maximum U_{m2} of the measured voltage U_m in curve II. As a result of the approach of the electrode tool 3, the pressure in the electrolyte 18 increases, causing the vapor and gas bubbles to dissolve so that the electrolyte 18 is homogenous and uniform in the gap and a high current density can be achieved with a small gap size. As a consequence, the electrical resistance decreases, which is apparent for the occurrence of a local minimum of the voltage U_m in curve II. As a result of the increasing distance $S(t)$ and a renewed formation of vapor and gas bubbles, the electrical resistance increases again leading to a second maximum U_{m2} of the voltage U_m . The application of electric power may be so large that the electrolyte begins to boil violently, giving rise to extra bubble formation in the gap 6. This causes a temporary increase of the electrical resistance of the electrolyte 18, which manifests itself as a local maximum U_{m1} of the voltage U_m .

Such a process of electrochemical machining is for instance described in more detail in document D2 of the list of referred documents that can be found at the end of this description, which is included by reference. A typical current density of the current pulses of normal polarity is 100 A/cm^2 , the length of the pulse period 3 ms and an oscillation frequency about 50 Hz. The oscillation amplitude may be 0.2 mm.

Curve I in Fig. 6 represents the variation of the size $S(t)$ of the gap between the workpiece 1 and the electrode tool 3 during a repeated movement relative to each other with a maximum size S_{max} and a minimum working distance S_{min} . Before establishing the working distance S_{min} , the distance $S(t)$ is reduced until the workpiece 1 and the electrode tool 3 come in contact with one another. By monitoring the voltage U_m , the instant of zero distance $S(t)$ can be determined and consequently the working distance S_{min} can be adjusted accurately. A typical working distance may be smaller than $50 \text{ }\mu\text{m}$. After the working distance of S_{min} has been set, a sequence of current pulses is applied, as illustrated with curve II in Fig. 6. After applying this sequence of pulses, the gap is enlarged to the size S_{max} to enable a renewal of the electrolyte as the electrolyte 18 will be rapidly saturated due to an inadequate flow rate during machining. Curve III of Fig. 6 gives an exploded view of the variation of the voltage U_m caused by a current pulse during a measuring period T_m . A more detailed description of this process of electrochemical machining is described in more detail in document D3 of the list of referred documents that can be found at the end of this description, which is included by reference.

As already illustrated with reference to the Figures 4 - 6, the measured voltage U_m across the gap, caused by the current flowing through the gap, shows significant variations in the relation of amplitude U_m versus time t . Fig. 7 shows some characteristic examples of measured voltages U_m during a predetermined measuring period T_m induced by applying current to an electrochemical cell. Curve I illustrates an example as may occur during applying current pulses in combination with an oscillatory movement such as illustrated with reference to Fig. 5. It is noted that only the voltage U_m within a measuring period T_m smaller than a pulse period is shown, leaving away the less informative parts of the measured voltage. Typically one local minimum is present at approximately at the instant of smallest size $S(t)$ of the gap 6. At the end the voltage U_m increases due to increasing size $S(t)$. Curve II illustrates an example with different process conditions, characterized by the occurrence of a local maximum due to a non-uniform electrolyte caused by generation of bubbles due to a high current density. Curve III gives an example illustrating even worsening process conditions, characterized by the occurrence of several local maxima.

In case of applying current pulses with a constant size $S(t)$ of the gap 6, such as illustrated with reference to Fig. 6, the feasible pulse duration may be a characteristic indicator of the process conditions. For example, curves IV, V and VI are illustrating different durations of the measured voltage U_m . It is noted that the corresponding current pulses as generated by a power supply unit 11 may all have the same pulse period. Only due to the rapidly increasing electrical resistance during application of the current pulse, the applied current cannot be maintained across the gap 6 and the measured voltage U_m decreases.

Curves VII, VIII, IX illustrates examples of different slopes of the forefront of measured voltage U_m , when applying current pulses with extremely short duration. For example, a favorable process condition may be obtained with a steep increase of the measured voltage U_m , as in that case less time is left for generation of bubbles in the electrolyte 18.

Curves X, XI and XII illustrate typical examples of the measured voltage U_m as may occur when applying a substantially constant current, as explained with reference to Fig. 4. The measuring period T_m is chosen such that significant changes in process conditions may be detected in time. For example with curve XI illustrating stable process conditions and with curve XII illustrating changing process conditions, due to for instance changing composition of the electrolyte 18 or changing flow of electrolyte. Curve X illustrates a process condition with increased noise of the measured voltage U_m . This may be indicative of near short circuit conditions, caused by local discharges.

It is remarked that the above given examples are merely illustrative of typical effects. Other effects, alone or in combinations may lead to a variety of measured forms.

Next will be explained how to quantify the information present in the measured voltage U_m , in accordance with the invention, in order to be employed as a control parameter in a method of controlling a process of electrochemically machining, either manually or automatically.

Fig. 8 shows a first embodiment of such a method according to the invention for determining a characteristic waveform of a measured voltage U_m such as shown in Fig. 7. The respective steps will be explained with reference to Fig. 9, showing the immediate results of quantifying. The method will be explained with reference to a measured voltage U_m as a function of time t as shown as curve I in Fig. 9. This curve I may be induced by a current pulse applied during an oscillating movement of electrode tool 3 and workpiece 1 relative to each other, according to a process of electrochemically machining as illustrated with

reference to Fig. 5 The measuring period T_m is chosen equal to the pulse period, which information may be obtained from the power supply unit 11. It is remarked that although the depicted curves seem to be continuous, in practice sampled and digitized points of the curves will be used. Preferably a table of sampled values $U_i(T_i)$ versus time instants T_i is used to characterize the measured voltage U_m as a function of time t . This is performed with a sampling step 31.

Subsequently, excluded from this table are samples during initial and final parts of the measured sampled voltage $U_s(t)$ that are occurring during a transitive process in the power supply unit 11. This is done in a cutting step 32 where an initial part T_a and a terminal part T_e , connected to a transient process are being excluded from the measuring period T_m to obtain a corrected measuring period T_m' . Information with respect to the size of these parts T_e and T_a may be obtained either from the power supply unit 11 or may be obtained by analyzing the measured samples. Alternatively, the size of T_e and T_a may be determined in advance. Further, the measuring period T_m may be chosen in advance such to exclude transient parts from the beginning. The resulting sampled form $U_s(t)$ after cutting is shown as curve II in Fig. 9.

Next, in a linearization step 33, a linear function $U_{lin}(t)$ is derived from the samples U_s determined so far. The linear function $U_{lin}(t)$ is characterized by the values U_a and U_e of the measured sampled voltage U_i at the beginning and at the end respectively of samples U_s resulting after cutting and is given by :

$$U_{lin}(t) = U_a + ((U_e - U_a) / T^*) \cdot t \quad [1]$$

with $T^* = T_m'$. Curve III in Fig. 9 shows an example of such a linear function $U_{lin}(t)$

Next, in a subtracting step 34, the linear function $U_{lin}(t)$ is subtracted from the sampled function $U_s(t)$ to obtain a differential function U_d according to :

$$U_d(t) = U_s(t) - U_{lin}(t) \quad [2]$$

The resulting differential function $U_d(t)$ is shown as curve IV in Fig. 9.

Subsequently, in a smoothing step 35, a smooth continuous function $U^*(t)$ is formed by conjugation of the differential function $U_d(t)$. This is done by symmetrically reflecting the differential function $U_d(t)$ relative to the horizontal and vertical axis, as shown

as curve V in Fig. 9. The resulting smooth function $U^*(t)$ is a periodically odd function, that has a continuous first derivative.

Next, in an expansion step 36, the function $U^*(t)$ is expanded in a Fourier series with Fourier-coefficients C_k and corresponding amplitudes A_k . As the function $U^*(t)$ is an odd function, all cosine coefficients will be equal to zero. Expansion is thus made by only sine coefficients. A typical result of such an expansion is shown in Fig. 10. Herein the amplitude A_k of the corresponding Fourier coefficients C_k are shown. As is generally known, the Fourier coefficients C_k represent trigonometric functions such as sine and cosine functions of different repetition period or wave length. The coefficient C_0 denotes merely an offset, the coefficients C_k with $k=1,2,\dots$ denoting the k numbered harmonics of an elementary sine or cosine function with repetition period $2T$ (of curve V in Fig. 9). The harmonic numbered k in this respect is denoting the trigonometric function with a repetition period equal to the $2T/k$. However, it is remarked that the definition of numbering is arbitrary.

The following step is a oscillating function building step 37, where a sinus function is build that corresponds to the oscillating movement of the electrode tool 3 and workpiece 1 relative to each other, according to a process described with reference to Fig. 5 with curve I. The distance $S(t)$ of the gap 6 is represented by the following function :

$$S(t) = \sin [\omega(t - T^*/2) + \pi/2] \quad [3]$$

with ω the oscillating frequency in rad/s. Curve VI illustrates this function $S(t)$. Analogous to the previous linearizing step 33, a linear function $S_{lin}(t)$ is build based on the sizes S_a and S_e of the function $S(t)$ at the start and the end of the corrected measuring period, as shown schematically with curve VI in Fig. 9 :

$$S_{lin}(t) = S_a + (S_e - S_a)/T^* \cdot T \quad [4]$$

Also analogously, this linear function $S_{lin}(t)$ is subtracted from the function $S(t)$ to obtain a differential function $S_d(t)$:

$$S_d(t) = S(t) - S_{lin}(t) \quad [5]$$

Next, still in the oscillating function building step 37, a smooth continuous function $S^*(t)$ is formed by conjugation of the differential function $S_d(t)$. This is done by symmetrically reflecting the differential function $S_d(t)$ relative to the horizontal and vertical axis, as shown as curve VII in Fig. 9. The resulting smooth function $S^*(t)$ is a periodically odd function, that has a continuous first derivative.

Next, in a second Fourier expansion step 38, this function $S^*(t)$ is expanded in a Fourier series with corresponding Fourier coefficients C^*k and amplitudes A^*k , again analogous to step 36.

In a subtracting step 39 the coefficients C_k are subtracted from the corresponding coefficients C^*k to obtain corrected coefficients $C'k$:

$$C'k = C_k - A \cdot C^*k \quad (k=1,2,\dots) \quad [6]$$

The value of A is defined by the method of least squares by minimizing the function :

$$\Phi(A) = \sum_{k=1,2,\dots} (C_k - A \cdot C^*k)^2 \quad [7]$$

The minimum of A takes places when:

$$A = \frac{\sum_{k=1,2,\dots} C_k \cdot C^*k}{\sum_{k=1,2,\dots} C^*k^2} \quad [8]$$

An example of a resultant series of corrected coefficients C_k with amplitude A_i is shown in Fig. 10.

It is remarked that the above given expansion of the measured voltage U_m within the measuring period, is one of several ways to expand. Expansion may equally take place in cosine functions, if an even function is more appropriate or may take place as a combination of sine or cosine functions. Moreover, the method according to the invention is not restricted to expansion in trigonometric functions only. Expansion may also take place in a series of other appropriate elementary functions.

Further it is noted that a conversion of the measured voltage from the time domain to the frequency domain, such as is done by the above-mentioned Fourier transformation, is not the only method to obtain the spectral composition. The spectral

information may equally be obtained by performing an autocorrelation in the time domain or by employing suitable frequency band filtering.

It is also noted that subtracting a linear function is not essential to the method of the invention, but is to be regarded as an advantageous embodiment. The same accounts to subtracting the coefficients corresponding to an oscillatory movement. Herewith it should be realized that the above given example of expansion has been illustrated with reference to a specific process, involving pulsed current with an oscillatory movement of electrode tool 3 on workpiece 1. In case of no relative movement during a measuring period, such subtraction may be less advantageous. On the other hand, different kinds of movements may be present and which need to be corrected for.

The above described may be performed employing with dedicated hardware, a general purpose computer programmed with suitable software or a combination of both. Further to increase speed, as typically every 20 ms a decision may be necessary, tables with sine and cosine values may be employed. The number of harmonics may be limited approximately to 10, as low frequency distortions can be described by 10 harmonics with a precision of about 1%.

Table 11 illustrates the assignment of characteristic series of Fourier coefficients C_k to corresponding types of process conditions. The values are of course limited to the process of electrochemical machining used, such as the one used for explaining the method of expansion. Other processes will lead to other values and to other typical types of process conditions. It is up to the skilled operator to determine the characteristic series of Fourier coefficients C_k and the corresponding assignment to process conditions, by means of trial or error. This may even depend on the type of workpiece to be machined.

A type 1 process condition is assigned to the absence of the harmonics 2–10, indicated with the value '0'. Type 1 process conditions are being characterized by appearing of a dark-gray or black film on the machining surface, high roughness and a low productivity caused by a low current density.

A type 2 process condition is assigned to the presence of the harmonic numbered 2 and 4 with a negative amplitude '-1' and of the harmonic numbered 3 with a positive amplitude '+1'. Type 2 process conditions are being characterized by the appearing of a dense dark file on the machining surface, high roughness, low productivity caused by boiling up of the electrolyte or reaching a limit value of gas-filling of the electrolyte.

A type 3 process condition is assigned to the presence of the harmonics numbered 2,3,4,5 and 6 with a negative amplitude. Type 3 process conditions are being

characterized by the appearing of a regular wavy surface along the electrolyte flow, a low precision of copying and a high power consumption.

An undefined process condition "u" is assigned to situations not recognized "*".

5 It should be realized that the values given in table 10 are only one example. The number of types of process conditions may be extended if necessary while several series of Fourier coefficients may be assigned to one type of process conditions.

10 Next, with reference to the Figures 19-21, various examples of Fourier coefficients C_k will be given, as a function of varying process control parameters. The process taken as example is a process employing an oscillating movement and current pulses as disclosed with reference to Fig. 5. The Fourier coefficients C_k and a horizontal bar 78, respectively representing the size and presence of n-numbered harmonics, will be shown for various waveforms constituted by the measured voltage U_m versus time t .

15 Fig. 19 shows the Fourier coefficients C_k as a function of the process control parameters for the gap size S and a minimal applied voltage across the gap U_{min} . U_{min} is related with the minimal voltage present during applying a pulse. The electrolyte pressure is kept constant at a value of 300 kPa. Shown are the measured voltage U_m and the value C_k of the corresponding Fourier coefficients. Curve I depicts the situation with $U_{min}=9,0$ V and $S=22$ μm , curve II with $U_{min}=5,0$ V and $S=18$ μm and curve III with $U_{min}=4,0$ V and $S=3$ 20 μm . The flattening waveform depicted by U_m versus time t , is reflected by the decrease of the Fourier coefficients C_k . A type I process condition as shown with bar 78 for curve I is gradually changed in a process condition with no harmonics as shown with bar 78 of curve III.

25 Fig. 20 shows the Fourier coefficients C_k primarily as a function of the process control parameter for the electrolyte pressure P_{in} for the same process with constant minimal applied voltage $U_{min}=10,0$ V and approximate constant gap size S . Curve I depicts the situation with $P_{in}=400$ kPa and $S=30$ μm , curve II with $P_{in}=100$ kPa and $S=46$ μm and curve III with $P_{in}=30$ kPa and $S=36$ μm . Reducing the pressure P_{in} results in the generation of a local maximum in the waveform constituted by U_m . This is reflected by 30 Fourier coefficients of alternating sign, leading to a type 3 process condition as shown by bar 78 of curve III.

Fig. 21 shows the Fourier coefficients C_k as a function from the gap size S of the same process. The electrolyte pressure P_{in} is kept at 400 kPa while the minimum applied voltage U_{min} is kept to 10,0 V. Curve I depicts the situation with $S=26$ μm , curve II with

S=36 μ m and curve III with S= 46 μ m. It can be seen that with an increasing size S, gradually a type 3 process condition is being obtained.

Fig.12 shows a further embodiment of the method according to the invention for deriving spectral information. Curve I of Fig. 12 shows an example of measured voltage Um in case of applying a current pulse. In this embodiment the high frequency information content is analyzed in stead of the low frequency content as defined by a number of up to 10 harmonics as described before. The high frequency content comprises harmonics substantially higher then 10. The indicated area 40 indicates typical high frequency variations. Curve II in Fig. 12 shows the measured voltage UmHF after amplification and high pass frequency filtering the voltage Um. The measuring period Tm should be chosen such that the large spikes 41 and 42 present at the beginning and at the end of the measured pulse, should be excluded. These spikes are mainly due to switching actions in the power supply circuit and are not characteristic of process conditions. The depicted curves I and II may be indicative of normal process conditions. However, curve III in Fig. 12 corresponds to a changed process condition, as indicated by the distortion 43. Curve IV shows again the amplified and high pass frequency filtered measured voltage UmHF. Two parts can be distinguished in this curve IV: a part 44 with relatively low amplitudes and a part 45 with relatively high amplitudes. The part 44 being indicative of a so-called before accident ECM regime. With an accident ECM regime is meant a process conditions with the occurrence of electrical discharges. The occurrence of such a process condition should be avoided as the electrode tool or workpiece may be damaged. The change in amplitude of the high frequency content as indicated with UmHF appears to be a good indicator of such a before accident ECM regime.

The occurrence of such high frequency content may be determined by the presence and change of amplitude of high numbered harmonics, for example higher than 10, as established by expanding the measured voltage Um in a Fourier series according to the method disclosed with reference to Fig. 8 and 9. However, alternatively an advantageous method is obtained by, as already indicated with reference to curves II and IV in Fig. 12, amplifying and high pass frequency filtering the measured voltage Um. This may be realized by for example a simple amplifier and a high pass frequency filter circuit. A typical amplifying factor may be 100 while a typical cut-off frequency should be greater than about 20 kHz in case of pulse period of 3 ms. It is noted that a pulse period of 3 ms has lowest numbered harmonics with frequencies ranging up to 10 kHz.

After having obtained the amplified and high pass frequency filter voltage U_{mHF} as shown in curve IV of Fig. 12, a further advantageous method is obtained by taking the absolute value thereof : AU_{mHF} . It is noted that the valued of U_m or U_{mHF} may be sampled and digitized, so all steps may be performed digitally. For example a number of
5 sampling points may be chosen equal to 2000 during a measuring period T_m . Next a running average IAU_{mHF} of AU_{mHF} may be obtained with respect to a specific interval, for instance of 300 points. Curve V in Fig. 12 illustrates two possibilities that may result: one curve 47 corresponding to a normal ECM process condition such as indicated with curve II and one curve 46 corresponding to a before accident ECM process condition corresponding
10 with curve IV. The occurrence of a difference between a reference value of IAU_{mHF} and an actual value, may be chosen as indicator.

Fig. 13 shows an embodiment of a control unit 12 of Fig. 2 for carrying out the method of the invention. Such a control unit 12 may be distinguished in two units: an evaluating unit 48 and a regulating unit 49. The evaluating unit 48 is used for determining the
15 frequency content of the measured voltage U_m (corresponding to either U_{m1} or U_{m2}) according to the method of the invention. The regulating unit 49 is used for controlling the process of electrochemically machining employing the results of the evaluating unit 48 and other measurement signals.

First an embodiment of an evaluating unit 48 for carrying out the method of
20 the invention will be explained. A sampling unit 50 is receiving the measured voltage U_{m1} or U_{m2} induced by the applied current to electrode tool 3 and workpiece 1, as shown with reference to Fig. 3. The sampling unit 50 receives a sampling signal T_m indicative of the sampling period. This sampling signal T_m is generated by the regulating unit 49 and is, in case of pulsed current, mainly determined by the employed pulse period. In case of a constant
25 current, predetermined values may be used. The sampling unit 50 selects parts of the measured voltage U_{m1} or U_{m2} in correspondence with the sampling signal T_m

The sampled signals are then supplied to a low frequency determining part comprising an analog-to-digital converter 51, a form function generating unit 52, a Fourier expansion unit 53 and an assignment unit 54. The form function generating unit 52 generates
30 a form function indicative of the sampled values of U_m during a sampling period corresponding to the measuring period T_m . The form function generating unit 52 further receives a signal $S2$ indicative of the relative movement of the electrode tool 3 and the workpiece 1. Herewith a form function indicative of this movement is being generated. The

generating of both form functions may be carried out with the method disclosed with reference to Fig. 8 and Fig. 9.

These form functions are expanded in a Fourier series with the Fourier expansion unit 53 in a manner as explained with reference to Fig. 8 and Fig. 9. The Fourier expansion unit 53 supplies corresponding Fourier coefficient signals C_k to monitoring means 13 for display and to assignment means 54. Assignment means 54 are assigning typical process conditions to characteristic series of Fourier coefficients C_k in a manner as explained with reference to table 1. A resulting signal T representing the type of process condition is being outputted to monitoring means 13 and to the regulating unit 49.

The sampled signals generated by the sampling unit 50 are also supplied to a high frequency determining part comprising a high pass filter 55, an amplifier 56, an absolute value unit 57, an averaging unit 58 and a difference unit 59. The sampled signals supplied to the high pass filter 55 may be analog or digital. As mentioned before, the high pass filter 55 should pass variations in the measured voltage U_m with frequencies from, for example, 20 kHz. The subsequent amplifier 56 is used to amplify the relative variations in voltage U_m . At this stage it is remarked that instead of using the amplified and filtered signals so far, the Fourier coefficients C_k such as generated by the Fourier expansion unit 53, provided that this unit is adapted to determine amplitudes of higher numbered harmonics.

The absolute value unit 58 takes the absolute value of the signal inputted while the averaging unit 58 determines a running average, both in accordance with the method disclosed with reference to Fig. 12. Finally, a difference unit 59 determines the difference between a result obtained with normal process conditions. A signal A_c representing the presence of a pre-accident process situation is supplied to the regulating unit 49.

It is noted that, the separate units in the evaluating unit 48 may be embodied as separate units of dedicated hardware or may be processing steps in a general software program loaded in a general purpose computer. Also combinations may be present, for instance, a Fourier expansion unit 53 may be implemented as an expansion board for a general purpose computer. Further the high frequency determining part may be embodied with analogue components.

Next the regulating unit 49 will be explained in more detail. The regulating unit 49 receives in addition to the signals already mentioned, amongst others, manually inputted control signals MAN , a signal P_{out} representing a pressure of the electrolyte 18, measured for example at an output of the electrochemical process unit 10, and a signal Z representing the position of the workpiece 1. The regulating unit 49 outputs current or

voltage supply selection signals SEL1, SEL2 ..., power supply control signals CI1, CU1,..., control signals S1 and S2 for controlling the feed rate V1 and the electrode speed V2 respectively and a control signal Pin for controlling a pressure of the electrolyte, for example a pressure at the input of the electrochemical process unit 10.

5 Next the operation of the regulating unit 49 will be explained in more detail, with reference to Figures 14-17, which show several methods according to the invention of controlling a process of electrochemically machining.

10 First, the high frequency information signal Ac and/or the type information signal T or Fourier coefficients signals Ck may be merely employed as limiting the operating range of the regulating unit 49. The regulating unit 49 controls the process of electrochemically machining within these limits. An advantageous control process for a process applying pulsed current and an oscillatory movement, employs as a process control parameters a pressure of the electrolyte 18, for instance the pressure Pin at the input of the electrochemical process unit 10. As the pressure is low, insufficient electrolyte flow will
15 result, while a high pressure may result in a local cavitation or turbulence in the electrolyte. A further advantageous control process, in case of the same process, employs as a process control parameter the relative phase ϕ between the oscillatory movement and the start of a current pulse. Preferably both process control parameters are being employed. The process parameters Pin and ϕ are chosen in such a manner as to optimize the value of the feed rate
20 V1.

 However, it has been found that several other advantageous embodiments according to the invention are obtained when controlling other process parameters such as the time during which current is being applied, either pulsed or constant and/or the type and amount of relative movement between the electrode tool 3 and the workpiece 1. It has been
25 found that undesired process conditions, as apparent from the spectral information derived from a measured voltage Um during a measuring period Tm, may be avoided by controlling these process parameters.

 For instance, Fig. 14 illustrates a first method of controlling employing as a first process control parameter the supply of the current Is continuously or intermittently and
30 as a second process control parameters the corresponding size S(t) of the gap 6. Curve I of Fig. 14 shows a first operational phase 60 when machining is done at a first size Smax and a second operational phase 61 when machining is done at a smaller size Smin of the gap 6. During the first operational phase 60 the current Is is applied continuously and during the second operational phase 61 the current Is is applied intermittently in pulse like periods, as

illustrated by curve II in Fig. 14. Curve III shows the voltage U_m as a function of time t . During the first operational phase 60, the voltage U_m is determined in first measuring periods T_{m1} and during the second operational phase 61 in second measuring periods T_{m2} . As can be seen in curve III, part 62 thereof shows a significant change of the voltage U_m during the first phase. This indicates a change in process conditions, which is being monitored by the evaluating unit 48. The change in process condition may for instance indicate the end of a feasible range of machining the workpiece 1 with a high feed rate. This may be due to reaching a specific stage in shaping the workpiece 1, leading to a variation in local size $S(t)$ of the gap 6. The evaluating unit 48 determines the corresponding type of process condition whereupon the regulating unit 49 reacts to by applying the current intermittently and at a shorter distance S_{min} . This enables to continue stable machining with an improved accuracy although with a lower feed rate of the workpiece 1.

Fig. 15 illustrates a second method of controlling employing as a first process control parameter the supply of current I_s continuously or intermittently and as a second process control parameter either a constant size $S(t)$ or an oscillating size $S(t)$ of the gap between electrode tool 3 and workpiece 1. Curve I of Fig. 15 illustrates a first operational phase 63 with a constant supply of current I_s at an initial size S_{int} and a second operational phase 64 with a pulsed supply of current I_s during an oscillating movement. During the measuring periods T_{m1} , at part 65 of the curve III, an increase in measured voltage U_m is measured by the evaluating unit 48, indicating for instance an increase of electrical resistance, caused by the formation of gas bubbles in the electrolyte 18. The regulation unit 49 causes the power supply unit 11 to apply only current during instants of smallest size S_{min} of an oscillatory movement. Thus avoiding formation of gas bubbles due to an increased electrolyte pressure in the gap 6 during the instants of smallest size. During the instants of largest sizes S_{max} of the oscillatory movement, no current is supplied and the liquid can be replenished. Changing from the first operational phase 63 to the second operational phase 64 enables maintaining stable process conditions. The voltage U_m is still measured during the pulses during measuring periods T_{m2} , in order to determine the limit of process control parameters such as the phase φ between the moment of smallest distance and the moment of application of the pulse.

Fig. 16 illustrates a third method of controlling employing as a first process control parameter the supply of a sequence of current pulses I_s at a first rate or at second rate, as illustrated by curve II, and as a second process control parameter the distance $S(t)$ as illustrated by curve I. Two characteristic operational phases 66 and 67 are shown. The

corresponding machining distances S1 and S2 are both obtained after bringing the workpiece 1 and electrode tool 1 in contact with each other. This enables a high positioning accuracy. As illustrated with parts 68, 69 and 70 of curve III in Fig. 16, the characteristic form of the measured voltage U_m is changing with successive pulses, indicating worsening process conditions. In this example the pulse forefront varies. This may be an indicator that the machining distance may be reduced. The evaluating unit 48 supplies this information to the regulating unit 49, where upon the machining distance is reduced to a smaller value S2. To enable stable process conditions, the pulse rate is increased by shortening the pulse duration. It has been found that shortening of the pulse duration has the effect of leaving less time for generation of gas like bubbles, such as molecular hydrogen gas in the electrolyte 18. Preferably the pulse duration should be chosen small enough to avoid either forming of nuclei of atomic hydrogen that precede the formation of molecular hydrogen gas or forming of molecular hydrogen gas as such. In an embodiment the pulse duration should not exceed the time required to form molecular hydrogen gas. From the parts 71 and 72 of the curve III, it can be seen that it may be difficult to apply sufficient electric power within the short pulse period, thus reducing the machining speed. However it has been found that even more electric power can be applied if the pulse duration is being reduced to extremely short values, ranging from 10 to 300 μs . It has been surprisingly found that the current density may be increased with such a short pulse duration to values between 4000 and 6000 A/cm^2 . However, essential for obtaining these high current densities is an extreme steep pulse up-slope with a value between 100-1000 ns. The pulse down-slope seems to be less relevant and should be less than 5 μs . The time duration or pauses between successive pulses should be large enough to enable escaping the generated molecular hydrogen gas, typically the duration between the pulses varies between 50 – 500 μs . The duration of a group of pulses varies between 20 – 1000 μs . However, as longer pauses also imply a reduction of machining rate, the pauses should not be taken to long. In a practical embodiment the ratio between a duration of a pause between the pulses and the pulse duration should be in a range between 2 and 10. The duration between applying groups of pulses range preferably between 20 – 5 ms. Preferably applying of pulses of these kind is done in combination with an oscillatory movement between electrode tool 3 and workpiece 1. The increase of local pressure within the gap 6 during the instant of smallest size $S(t)$ of the gap 6 is advantageous in avoiding formation of gas bubbles. It is noted that with the extreme short pulses, the allowable electric field intensities in the gap may range between 2500 V/cm to 25000 V/cm with sizes of the gap between 5 μm to 45 μm .

It is noted that a high local pressure also results in avoiding formation of gas bubbles. Although the electrolyte input pressure P_{in} may be 2 bar, a local pressure may increase to 50 bar. In that case boiling will only occur at much higher temperatures.

Further the physical effect obtained under these extreme short pulses may
5 similar to a local melting of the work piece. The local melt being formed in small ionized channels where after the molted material is immediately dispersed through the electrolyte.

Next a fourth method is illustrated with reference to Fig. 17. Curve I shows the variation of the size $S(t)$ versus the time t . Before establishing the machining distance S_{min} , the electrode tool 3 contacts or taps the workpiece 1. Curve II in Fig. 17 illustrates that a
10 sequence of machining current pulses with a normal polarity is being applied. As indicated by curve III in Fig. 17, the variation 73 of measured voltage U_m induced by a current pulse may indicate, by evaluation of the Fourier coefficients, the formation of a sedimentation layer on the electrode tool 3. The electrode tool 3 itself may be made of metals like copper, chromium or chromium-nickel and the like. However metals like titanium will not lead to the
15 formation of an oxide layer. This is also not likely to happen as during machining the electrode tool 3 is being kept at a negative voltage relative to the workpiece 1. However, what might happen is the attraction of positively charged particles such as remnants of acids, present in the electrolyte and the formation of a layer thereof on the electrode tool 3. These particles are not strongly attached to the electrode tool by due to a chemical reaction and
20 therefore may be removed therefrom by applying temporally a positive voltage to the electrode tool 3. This is realized by inducing a current pulse 74 of a negative polarity such as illustrated in curve II. It is noted, that alternatively the same result may be obtained by applying a voltage pulse of inverted polarity. Applying such pulses causes the loosely attached sediments to go in solution again. In addition, the remnants of metals in the
25 electrolyte such as chromium and nickel, which may be deposited on the electrode, known as the plating effect, may be removed by the above mentioned cleaning pulses. Applying cleaning pulses may be induced by changed geometrical values but also a reduced amount of flow of electrolyte.

Fig. 22 illustrates a next advantageous method of combining two kinds of
30 voltage pulses of inverted polarity with a current pulse of normal polarity. Curve I depicts the generation of a sequence of current pulses of normal polarity with amplitude I_{g1} induced by control signal $CI2$ as described with reference to Fig. 3. Curve II depicts the generation of a sequence of voltage pulses of opposite polarity with a first amplitude U_c and a second amplitude U_n induced by control signal $CU2$ as described with reference to Fig. 3. The

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voltage pulses with amplitude U_n serving to dissolve a passivating layer formed on the workpiece 1, in accordance with the method disclosed in more detail in document D2 in the list of referred documents which can be found at the end of the description. A passivation layer is formed by a dark oxide film. The required voltage depassivation voltage U_n should preferably lie between the polarization voltage U_{pol} , which is explained with reference to curve IV, and the voltage U_{nmax} at which the electrode begins to dissolve. This is explained in detail in document D2. The voltage pulses with amplitude U_c serve to clean the electrode tool 3 in a manner as disclosed with reference to Fig. 17. The value U_c is preferably larger than the value U_n , the last one chosen such as not to dissolve the electrode tool 3. The disadvantage of the higher value of U_c being thus dissolution of the electrode tool 3. This may be prevented by employing non dissolving electrode materials such as platinum or by employing a passivating electrolyte such as sodium nitrate in combination with a chromium-steel electrode. With this last choice of electrolyte and electrode material, the value U_c should not be larger than 3,6 V as otherwise the passivating functioning is stopped and the electrode will start to dissolve. Preferably the value is kept below 2 V. How many and with which length the cleaning pulses have to be applied, will have to be determined by trial and error. For instance after every 20 s machining applying one cleaning pulse of 1 s.

Curve III shows the combined current I_g passing the gap 6 as a result of the applied current and voltage pulses. The current pulse of normal polarity has an amplitude I_{g1} , the voltage pulses of opposite polarity induce a maximum current of I_{g2} and I_{g3} . Curve IV shows the measured voltage U_m across the gap 6. The voltage pulses of opposite polarity having amplitudes of U_{m1} and U_{m2} . The voltage U_m measured immediately after termination of the current pulse while no other pulses are being applied, is called the polarization voltage U_{pol} , eventually decreasing to zero.

Thus an advantageous method is obtained by choosing as a process control parameter the application of such an electrode tool cleaning pulse, if the evaluation of the process condition such as apparent from the spectral content of the measured voltage U_m , indicates pollution of the electrode tool. Especially in case of electrolyte which has been used for a long time, a deposition of dissolved metal ions of the dissolved workpiece may occur as black layer along the total area of the electrode tool. This is called plating and may effect the geometrical dimensions. Another contamination is deposition of a hydroxide layer near the electrolyte outflow opening within the gap. This does not only effect the geometrical dimension but also the flow rate of the electrolyte. It is noted that such an electrode tool cleaning pulse may also applied in advance, at predetermined instants.

Fig. 18 illustrates a next advantageous embodiment, based on an oscillatory movement as indicated by curve I in Fig. 18. Machining current pulses 76 are being applied as indicated by curve III. An advantageous process control parameter is obtained by applying so-called passivation pulses 77 of the same polarity but with smaller amplitude. These pulses are being applied when the gape size is large, so as to avoid undesired distortions of the shape. As disclosed in more detail in document D3, in the list of referred documents that can be found at the end of this description, such passivation pulses improve the machining copying accuracy as a passivation layer is formed on those surface of the workpiece1 which is not or less to be machined. Evaluation of the process conditions by the spectral content may induce a change from a relatively low precision machining process to a relatively high precision machining process and vice versa. This may also be induced after having machined a predetermined amount of material out of a total amount to be machined, for instance 80 μm out of a total of 120 μm .

It is remarked, that although the several current and voltage sources are shown to be incorporated in one unit, in practice the sources may be placed apart and connected by suitable connection means to the electrochemical process unit 10 and the control unit 12. Further, one or more sources may be missing or one ore more sources may be added, in dependence of the method according to the invention.

Further is remarked to a transition from one type of process of electrochemically machining to another type, may be performed either automatically or manually. Manually changing may imply the changing of the electrochemical process unit 10, of the power supply unit 11 or of a current or voltage source.

Although the invention has been described with reference to preferred embodiments thereof, it is to be understood that these are not limitative examples. Thus, various modifications may become apparent to those skilled in the art, without departing from the scope of the invention, as defined by the claims. The invention can be implemented by means of both hardware and software, and that several "means" may be represented by the same item of hardware. Further, the invention lies in each and every novel feature or combination of features. It is also remarked that the word 'comprising' does not exclude the presence of other elements or steps than those listed in a claim. Any reference signs do not limit the scope of the claims.

LIST OF REFERRED DOCUMENTS:

- (D1) International Patent Publication WO 99/34949, in the name of applicant, (PHN 16713)
- 5 (D2) International Patent Publication WO 97/03781, in the name of applicant, (PHN 15754)
- (D3) International Patent Publication WO 99/51382, in the name of applicant, (PHN 16835)

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